GENERAL

Control System
The 2022 NI Driver Station software does not run on machines employing Windows 7 (e.g. Classmate PCs or Acer Aspire PCs distributed in Kickoff Kits from 2010-2016) because NI no longer supports Windows 7 as Microsoft ended support for it on January 14, 2020.

Field Tour Videos
The narration in the 2022 Field Tour Video: Hub states an incorrect number of AUTO CARGO required to decrease the CARGO BONUS threshold (states 4 instead of 5). A note has been added in the video description, the close captioning has been updated, and a pop-up has been edited in to correct the number.

Kit of Parts
Drive Base Kit
- Due to a delivery error, some Drive Base Kits shipped without the 160-tooth belts (part number 800-5M-15).
- Due to a manufacturing error, some Drive Base Kits shipped with out-of-spec hubs (part number am-4124). The issue is that the center hex hole is not concentric with rest of hub, which could cause assembly and performance issues. To check your hub and learn more about this issue, please refer to this document published by AndyMark. Some hubs have already been replaced by Kickoff locations that received “good” hubs to distribute with the Kickoff Kits.
- We’re so sorry for these disruptions. Please make sure to inventory your Kickoff Kit and report any missing/damaged/out-of-spec items, including belts and hubs if applicable, using the replacement parts request system (described on the Kickoff Kit section of the Kit of Parts page) by noon, Friday January 14, 2022.

REV Robotics Compliant Wheel Part Number
The part number listed on the REV Robotics box (in the Everyone Tote) for the compliant wheel should be REV-21-2030.

Voucher Book
Consider adding the following Voucher Suppliers to the checklist in your Kickoff Kit and at the start of the 2022 Virtual Kit Catalog:
- Swyft Robotics
- TE Connectivity
- monday.com
- Upverter

Please note that the Digi-Key voucher does not apply to Marketplace products.

The following vouchers do not require a code from the team’s dashboard (i.e. the “Access Code:" field on their pages should be "n/a"): Digi-Key, DriveWorks, Mastercam, One IPM, and SolidProfessor.

Kit of Parts Webpage
A link to a SOLIDWORKS video describing how to access models of Kickoff Kit items has been added to the Kickoff Kit section of the page.
**Playing Field Assets**

The following assets have been added:

- a link to a [SOLIDWORKS blog](#) with additional information about using SOLIDWORKS field assets.
- field CAD in Onshape
  - [Full Version](#)
  - [Light-weight Version](#) (some nuts and bolts removed to improve load time, recommended for use with Chromebooks or if limited internet connection)
- additional VR tools and references from AutomationDirect.com
  - a link to AutomationDirect.com’s [Oculus Quest Support Page](#)
  - [Oculus Quest installation instructions](#)
  - a link to AutomationDirect.com’s [SteamVR Support Page](#)
  - [VR Experience for SteamVR](#)
- [Machine Learning imagery](#) from WPI
- drawing [TE-22330](#) which details the Team Element: Cable Protector
- flat versions of the UPPER HUB Plastic (TE-22197) and UPPER HUB Vision Plastic (TE-22201) are included as STEP and SOLIDWORKS Part files in the [Complex Hub Team Element zip packet](#)
- specific links to Team Element assembly drawings in the [Drawings section of the Playing Field Page](#).

The following assets have been modified:

- **Team Element: Complex Hangar**
  - A note has been added to TE-22310 to clarify the location of LOW RUNG relative to the other RUNGS.
  - A note has been added to TE-22316 and TE-22322 to clarify RUNG heights when floor protection is absent.
  - The LOW RUNG has been raised by ½ in. on TE-22316 to better match the official FIELD.
- **Rapid React specific** drawing package (Official Element: HUB)
  - The angle of the plastic ramp in the LOWER EXIT has changed from 5° to 7½° and is reflected in the FIRST official CAD model, GE-22324, and all parent assemblies.
- **Team Element: Hub Complex Read Me** has been updated to change the quantity of 4 in. x 4 in. x 8 ft. lumber pieces from 6 to 8.

**SECTION 5.8 Vision Targets**

The distance from FIELD carpet to the top of the target assembly is 8 ft. 8 in. (~264 cm); the distance from FIELD carpet to the bottom of the vision tape is 8 ft. 5½ in. (~258 cm).
### SECTION 6.1 SETUP

Figure 6-1 is updated to correct the starting location for CARGO not staged in ROBOTS.

*Figure 6-1 MATCH setup*

### SECTION 7.2 ROBOT TO ROBOT INTERACTION

**G210**  
**During AUTO, no defense.** During AUTO, a ROBOT with any part of its BUMPERS on the opposite side of the FIELD (i.e. on the other side of the CENTER LINE from its ALLIANCE'S TARMACS) may contact neither an opponent ROBOT nor CARGO still in its staged location on the opposite side of the FIELD nor an opponent ROBOT.

Violation: TECH FOUL

### SECTION 8.4 DURING THE MATCH: AUTO

**H404**  
**AUTO CARGO delivery.** During AUTO, CARGO may only be introduced to the FIELD by a HUMAN PLAYER in a TERMINAL AREA.

Violation: FOUL per CARGO.

### SECTION 8.5 DURING THE MATCH

**H504**  
**TELEOP CARGO delivery.** During TELEOP, CARGO may only be introduced to the FIELD

A. by a HUMAN PLAYER and
B. through the GUARD.

Violation: FOUL per CARGO.

### SECTION 9

Throughout this document, the acronym PCH (Pneumatic Control Hub) is changed to PH (Pneumatic Hub).
**SECTION 9.5 MOTORS & ACTUATORS**

**Table 9-1 Motor allowances**

<table>
<thead>
<tr>
<th>Motor Name</th>
<th>Part Numbers Available</th>
</tr>
</thead>
<tbody>
<tr>
<td>Current/former KOP automotive</td>
<td>Denso AE235100-0160</td>
</tr>
<tr>
<td>motors</td>
<td>Denso 5-163800-RC1</td>
</tr>
<tr>
<td></td>
<td>Denso 262100-3030</td>
</tr>
<tr>
<td></td>
<td>Bosch 6 004 RA3 194-06</td>
</tr>
<tr>
<td></td>
<td>Johnson Electric JE-PLG-149</td>
</tr>
<tr>
<td></td>
<td>Johnson Electric JE-PLG-410</td>
</tr>
</tbody>
</table>

R503  *Power (most) actuators off of approved devices.* With the exception of servos, fans, or motors integral to sensors of COTS computing devices permitted in R501, each actuator must be controlled by a power regulating device. The only power regulating devices for actuators permitted on the ROBOT include:

- Relay modules,
  - Spike H-Bridge Relay (P/N 217-0220 and SPIKE-RELAY-H),
  - Automation Direct Relay (P/N AD-SSR6M12-DC-200D, AD-SSRM6M25-DC-200D, AD-SSR6M45-DC-200D), and
  - Power Distribution Hub (PDH) switched channel (P/N REV-11-1850) for controlling non-actuator CUSTOM CIRCUITS only.

R504  *Don’t overload controllers.* Each power regulating device may control electrical loads per Table 9-2. Unless otherwise noted, each power regulating device shall control 1 and only 1 electrical load.

**Table 9-2 Power regulating device allotments**

<table>
<thead>
<tr>
<th>Electrical Load</th>
<th>Motor Controller</th>
<th>Relay Module</th>
<th>Pneumatics Controller</th>
</tr>
</thead>
<tbody>
<tr>
<td>AndyMark PG</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>KOP Automotive</td>
<td>Yes (up to 2 per controller)</td>
<td>Yes</td>
<td></td>
</tr>
<tr>
<td>Motors</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>NeveRest</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Snow Blower Motor</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>REV Robotics HD Hex</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

R505  *Control servos safely.* Servos must be connected to, and only to, 1 of the following:

- PWM ports on the roboRIO,
- PWM ports on a WCP Spartan Sensor Board (P/N WCP-0045), or
- REV Robotics Servo Power Module (P/N REV-11-1144), or
- REV Robotics Servo Hub (P/N REV-11-1855).

**SECTION 9.6 POWER DISTRIBUTION**

R615  *Power roboRIO as specified.* The roboRIO power input must be connected to either:

- the terminals of 1 of the non-switchable fused channels on the PDH (20,21,22) with a 10A fuse installed in the associated fuse holder.

No other electrical load shall be connected to these terminals that channel.
**SECTION 9.8 PNEUMATIC SYSTEM**

R812  *Pressure switch requirements.* The pressure switch must be connected to the high-pressure side of the pneumatic circuit (i.e. prior to the pressure regulator) to sense the stored pressure of the circuit.

It must be either:

B. REV Robotics P/N REV-11-1107

The analog output of the sensor must be connected directly to 1 of the analog pressure sensor inputs analog input 0 of the PCH controlling the compressor.

**SECTION 11.1 MATCH SCHEDULE**

The top-right label in Figure 11-1 was updated as follows: PLAYER STATION DRIVER STATION.

![Figure 11-1 Sample MATCH schedule]

**SECTION 11.4 MEASUREMENT**

T401  *Freeze, ROBOT.* During the period when the ARENA is open for measurement, ROBOTS can be enabled, but cannot move (i.e. neither the ROBOT, nor anything on the ROBOT, can move) may neither drive, extend outside their frame perimeter, nor can they interact with (e.g. score, push, pickup, etc.) CARGO, the HUB, the HANGAR, or other FIELD elements.

Violation: Verbal warning. If subsequent violations at any point during the event or egregious YELLOW CARD.

**SECTION 11.8.1.4 AWARDS**

In many ways, the team’s experience in being selected for awards, especially the Chairman’s Award, the Engineering Inspiration Award, and the Rookie All Star Award (which is optional for District Championship events), is beyond measure, and could not be fully captured in its entirety by any points-based system.

**SECTION 11.8.2 DISTRICT CHAMPIONSHIP ELIGIBILITY**

<table>
<thead>
<tr>
<th>District Championship</th>
<th>Capacity</th>
</tr>
</thead>
<tbody>
<tr>
<td>Michigan State Championship</td>
<td>200</td>
</tr>
<tr>
<td></td>
<td>160</td>
</tr>
</tbody>
</table>
## SECTION 12 GLOSSARY

<table>
<thead>
<tr>
<th>Term</th>
<th>Definition</th>
</tr>
</thead>
<tbody>
<tr>
<td>CONTROL</td>
<td>the state of a CARGO if any of the following are true:</td>
</tr>
<tr>
<td></td>
<td>A. the CARGO is fully supported by the ROBOT,</td>
</tr>
<tr>
<td></td>
<td>B. the CARGO travels across the FIELD such that when the ROBOT changes</td>
</tr>
<tr>
<td></td>
<td>direction,</td>
</tr>
<tr>
<td></td>
<td>C. the CARGO travels with the ROBOT, the ROBOT is holding CARGO against</td>
</tr>
<tr>
<td></td>
<td>a FIELD element in attempt to guard or shield it, or</td>
</tr>
<tr>
<td></td>
<td>D. the ROBOT is preventing a CARGO from leaving a LOWER EXIT.</td>
</tr>
</tbody>
</table>